

Load Flow and Voltage Instability Analysis Using MI Power Software

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Abstract: The load flow study or power flow analysis is very important for planning, control and operations of existing systems as well as planning its future expansion. The satisfactory operation of the system depends upon knowing the effects of interconnections, new loads, new generating stations or new transmission lines etc., before they are installed. It also helps to determine the best size and favorable locations for the power capacitors both for the improvement of the power factor and also raising the bus voltage of the electrical network. They help us to determine the best locality as well as optimal capacity of the proposed generating stations, substations or new lines. For this work the Fast Decoupled method is used for numerical analysis. This type of analysis is useful for solving the power flow problem in different power systems. voltage instability takes on the form of a dramatic drop of transmission system voltages, which may lead to system disruption it is a factor leading to limit power transfer. The objective of this paper is to describe load flow studies using Fast Decoupled Method and voltage instability analysis using MI Power software.

Keywords: Power flow analysis, Fast Decoupled Method, voltage instability, MI Power software.

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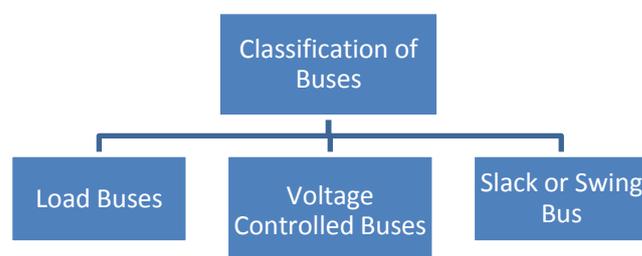
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I. INTRODUCTION

The Load flow problem consists of calculation of voltage magnitude and its phase angle at the buses. And also the active and reactive lines flow for the specified terminal or bus conditions. Load flow studies are used to ensure that electrical power transfer from generators to consumers through the grid system is stable, reliable and economic. Conventional techniques for solving the load flow problem are iterative, using the Newton-Raphson or the Gauss-Seidel methods. Depending upon the quantities specified for the buses, they are classified into three types namely load bus, generator bus or voltage controlled bus and slack bus or swing bus or reference bus.

II. BUS CLASSIFICATION

Buses are classified according to which two out of the four variables are specified Load bus: No generator is connected to the bus. At this bus the real and reactive power are specified and it is desired to find out the voltage magnitude and phase angle through load flow solutions. It is required to specify only Pd and Qd at such bus as at a load bus voltage can be allowed to vary within the permissible values.



Load Bus : In these buses no generators are connected and hence the generated real power P_{Gi} and reactive power Q_{Gi} are taken as zero. The load drawn by these buses are defined by real power $-P_{Li}$ and reactive power $-Q_{Li}$ in which the negative sign accommodates for the power flowing out of the bus. This is why these buses are sometimes referred to as P-Q bus. The objective of the load flow is to find the bus voltage magnitude $|V_i|$ and its angle δ_i

Generator bus or voltage controlled bus: Here the voltage magnitude corresponding to the generator voltage and real power P_g corresponds to its rating are specified. It is required to find out the reactive power generation Q_g and phase angle of the bus voltage. Slack (swing) bus: For the Slack Bus, it is assumed that the voltage magnitude $|V|$ and voltage phase are known, whereas real and reactive powers P_g and Q_g are obtained through the load flow solution

Slack or Swing Bus : Usually this bus is numbered 1 for the load flow studies. This bus sets the angular reference for all the other buses. Since it is the angle difference between two voltage sources that dictates the real and reactive power flow between them, the particular angle of the slack bus is not important. However it sets the reference against which angles of all the other bus voltages are measured. For this reason the angle of this bus is usually chosen as 0° . Furthermore it is assumed that the magnitude of the voltage of this bus is known.

Now consider a typical load flow problem in which all the load demands are known. Even if the generation matches the sum total of these demands exactly, the mismatch between generation and load will persist because of the line I^2R losses. Since the I^2R loss of a line depends on the line current which, in turn, depends on the magnitudes and angles of voltages of the two buses connected to the line, it is rather difficult to estimate the loss without calculating the voltages and angles. For this reason a generator bus is usually chosen as the slack bus without specifying its real power. It is assumed that the generator connected to this bus will supply the balance of the real power required and the line losses.[7]

III. Fast Decoupled Method

The Fast Decoupled Power Flow Method is one of the improved methods, which is based on a simplification of the Newton-Raphson method and reported by Stott and Alsac in 1974. This method, like the Newton-Raphson method, offers calculation simplifications, fast convergence and reliable results and became a widely used method in load flow analysis. Generally the power system have very high X/R ratio[1]. Hence the real power changes are less sensitive to change in voltage magnitude $|V|$ but it is more sensitive for changes in phase angle δ . Whereas the reactive power are more sensitive to changes in voltage magnitude and less sensitive for change in phase angle δ . Therefore it is reasonable to set J_2 and J_3 of Jacobian matrix to zero. Hence the equation for ΔP and ΔQ becomes:

$$\begin{bmatrix} \Delta P \\ \Delta Q \end{bmatrix} = \begin{bmatrix} J_1 & 0 \\ 0 & J_4 \end{bmatrix} \begin{bmatrix} \Delta \theta \\ \Delta V \end{bmatrix} \text{----- (1)}$$

By solving this we get two decoupled equations which require less time to solve as compared with N-R method. Hence finally after solving the above equations we get,

$$\frac{\Delta P}{V} = [B'] \Delta \theta \text{-----(2)}$$

$$\frac{\Delta Q}{V} = [B''] \Delta V \text{-----(3)}$$

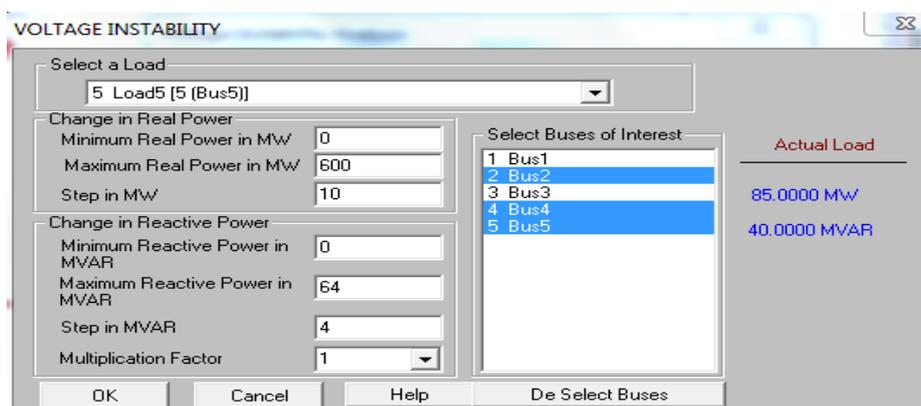
Here B' and B'' are the bus susceptance matrixes *i.e.* it is imaginary part of admittance matrix Y_{bus} . The bus susceptance matrix is constant and required to evaluate only once at beginning of the iterations. B' is the order of $(n-1)$. For voltage regulated buses the Q_i are not specified and hence the corresponding rows and columns of the Y_{bus} matrix are eliminated, hence we get B'' matrix of the order of $(n-1-m)$ where 'n' is the total number of buses and 'm' is the number of voltage controlled buses. The fast decoupled method requires more iteration than N-R method, but the time required is considerably less and we get rapidly the power flow solutions.[8]

IV. Mi Power Software

Mi Power is a highly interactive, user friendly windows based Power System Analysis package. It includes a set of modules for performing a wide range of power system design and analysis study. Mi Power features include a top notch Windows GUI with centralized database. Steady state, transient and electromagnetic transient analysis can be performed with utmost accuracy and tolerance. Designed to assess the risk of Voltage instability and margin of stability during sudden disturbances, under steady state conditions. It ranks the load buses based on the L-index value and the highest L-index indicates the system collapse point. The value of

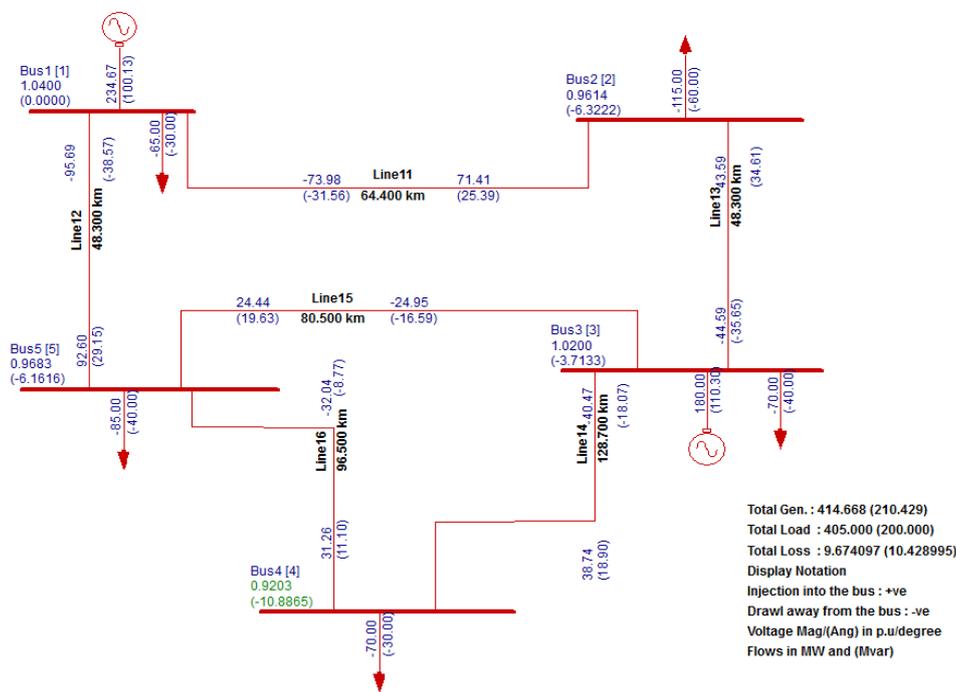
not able to maintain the voltage at all buses in the system remain unchanged after the system is being subjected to a disturbance.in this paper to perform voltage instability consider bus no 2, 4 and 5 of five bus system and plot the instability curve. In this paper to perform load flow analysis and voltage instability analysis Consider load variation at bus 5 for the voltage instability analysis with following data.

Power	Minimum	Maximum	Step
Real power (MW)	0	600	10
Reactive power (MVAR)	0	64	4



VII. Summary Of Result

Load flow analysis result (Fast Decoupled method):When perform load flow studies on 5 bus system using fast decoupled method using Mi Power software the following result we got.



[Figure2: 5 bus system result with load flow analysis]

BUS VOLTAGES AND POWERS									
NODE NO.	FROM	V-MAG	ANGLE	MW GEN	MVAR GEN	MW LOAD	MVAR LOAD	MVAR COMP	
	NAME	P. U.	DEGREE						
1	Bus1	1.0400	0.00	234.668	100.127	65.000	30.000	0.000	
2	Bus2	0.9614	-6.32	0.000	0.000	115.000	60.000	0.000	
3	Bus3	1.0200	-3.71	180.000	110.302	70.000	40.000	0.000	
4	Bus4	0.9203	-10.89	0.000	0.000	70.000	30.000	0.000	
5	Bus5	0.9683	-6.16	0.000	0.000	85.000	40.000	0.000	
NUMBER OF BUSES EXCEEDING MINIMUM VOLTAGE LIMIT (@ mark) : 1 NUMBER OF BUSES EXCEEDING MAXIMUM VOLTAGE LIMIT (# mark) : 0 NUMBER OF GENERATORS EXCEEDING MINIMUM Q LIMIT (< mark) : 0 NUMBER OF GENERATORS EXCEEDING MAXIMUM Q LIMIT (> mark) : 0									
LINE FLOWS AND LINE LOSSES									
SLNO	CS	FROM	TO	FORWARD	LOSS	%			
		FROM	TO	MW	MVAR	MW	MVAR	LOADING	
		NAME	NAME						
1	1	Bus1	Bus2	73.981	31.556	2.5683	6.1609	77.34	
2	1	Bus1	Bus5	95.687	38.571	3.0885	9.4234	99.24	
3	1	Bus2	Bus3	-43.587	-34.605	1.0062	1.0445	56.01	
4	1	Bus3	Bus4	40.469	18.066	1.7249	-0.8387	43.47	
5	1	Bus3	Bus5	24.947	16.387	0.5056	-3.0406	32.47	
6	1	Bus4	Bus5	-31.257	-11.096	0.7806	-2.3206	34.47	
! NUMBER OF LINES LOADED BEYOND 125% : 0 # NUMBER OF LINES LOADED BETWEEN 100% AND 125% : 0 @ NUMBER OF LINES LOADED BETWEEN 75% AND 100% : 2 \$ NUMBER OF LINES LOADED BETWEEN 50% AND 75% : 1 ^ NUMBER OF LINES LOADED BETWEEN 25% AND 50% : 3 & NUMBER OF LINES LOADED BETWEEN 1% AND 25% : 0 * NUMBER OF LINES LOADED BETWEEN 0% AND 1% : 0									
ISLAND FREQUENCY SLACK-BUS CONVERGED(1)									
1	50.0000	1	0						
SUMMARY OF RESULTS									
TOTAL REAL POWER GENERATION :				414.668 MW					
TOTAL REAL POWER INJECT, -ve L :				0.000 MW					
TOTAL REACT. POWER GENERATION :				210.429 MVAR					
GENERATION pf :				0.892					
TOTAL SHUNT REACTOR INJECTION :				-0.000 MW					
TOTAL SHUNT REACTOR INJECTION :				-0.000 MVAR					
TOTAL SHUNT CAPACIT. INJECTION :				-0.000 MW					
TOTAL SHUNT CAPACIT. INJECTION :				-0.000 MVAR					
TOTAL TCSC REACTIVE DRAWL :				0.000 MVAR					
TOTAL SPS REACTIVE DRAWL :				0.000 MVAR					
TOTAL UPFC FACTS. INJECTION :				-0.00000 MVAR					
TOTAL SHUNT FACTS. INJECTION :				0.000 MVAR					
TOTAL SHUNT FACTS. DRAWAL :				0.000 MVAR					
TOTAL REAL POWER LOAD :				405.000 MW					
TOTAL REAL POWER DRAWAL, -ve g :				0.000 MW					
TOTAL REACTIVE POWER LOAD :				200.000 MVAR					
LOAD pf :				0.897					
TOTAL COMPENSATION AT LOADS :				0.000 MVAR					
TOTAL HVDC REACTIVE POWER :				0.000 MVAR					

Zone wise distribution	
Description	Zone # 1
MW generation	414.6684
MVAR generation	210.4289
MW load	405.0000
MVAR load	200.0000
MVAR compensation	0.0000
MW loss	9.6741
MVAR loss	10.4290
MVAR - inductive	0.0000
MVAR - capacitive	0.0000

Zone wise export(+ve)/import(-ve)	
Zone # 1 MW & MVAR	
1	----

Area wise distribution	
Description	Area # 1
MW generation	414.6684
MVAR generation	210.4289
MW load	405.0000
MVAR load	200.0000
MVAR compensation	0.0000
MW loss	9.6741
MVAR loss	10.4290
MVAR - inductive	0.0000
MVAR - capacitive	0.0000

Date and Time : Tue May 29 15:12:08 2018

Voltage instability result report:

VOLTAGE INSTABILITY ANALYSIS								
CASE NO :	1	CONTINGENCY :	0					
SCHEDULE NO :	0	CONTINGENCY NAME : Base Case						
%% First Power System Network								
LARGEST BUS NUMBER USED :	5	ACTUAL NUMBER OF BUSES :	5					
NUMBER OF 2 WIND. TRANSFORMERS :	0	NUMBER OF 3 WIND. TRANSFORMERS :	0					
NUMBER OF TRANSMISSION LINES :	6	NUMBER OF SERIES REACTORS :	0					
NUMBER OF SERIES REACTORS :	0	NUMBER OF SERIES CAPACITORS :	0					
NUMBER OF BUS COUPLERS :	0	NUMBER OF SHUNT CAPACITORS :	0					
NUMBER OF SHUNT REACTORS :	0	NUMBER OF SHUNT REACTORS :	0					
NUMBER OF SHUNT IMPEDANCES :	0	NUMBER OF GENERATORS :	2					
NUMBER OF LOADS :	5							
NUMBER OF FILTERS :	0							
NUMBER OF HVDC CONVERTERS :	0							

NUMBER OF ZONES :	1							
PRINT OPTION :	3 (BOTH DATA AND RESULTS PRINT)							
PLOT OPTION :	0 (NO PLOT FILE GENERATION)							
BASE MVA :	100.000							
NOMINAL SYSTEM FREQUENCY :	50.000							

CIRCUIT BREAKER RESISTANCE (PU) :	0.000000							
CIRCUIT BREAKER REACTANCE (PU) :	0.000100							
TRANSFORMER R/X RATIO :	0.050000							

BUS DATA								
NODE	STAT	ZONE	BUS-KV	NAME	VMAG-PU	VANG-DEG	PGEN-MW	QGEN-MR
						PLOAD-MW	QLOAD-MR	QCOMP-MR
1	1	1	138.000	Bus1	1.0400	0.000	234.670	100.130
2	1	1	138.000	Bus2	0.9614	-6.322	0.000	0.000
3	1	1	138.000	Bus3	1.0200	115.000	60.000	110.300
4	1	1	138.000	Bus4	0.9203	-10.886	0.000	0.000
5	1	1	138.000	Bus5	0.9683	-6.162	0.000	0.000
						85.000	40.000	0.000

TRANSMISSION LINE DATA								
STAT	CKTS	FROM	TO	TO	RP(P.U)	XP(P.U)	BP/2(PU)	
		FROM	TO	TO				
		NAME	NAME	NAME				
3	1	1	Bus1	Bus2	0.04200	0.16800	0.02050	
3	1	1	Bus1	Bus5	0.03100	0.12600	0.01550	
3	1	2	Bus2	Bus3	0.03100	0.12600	0.01550	
3	1	3	Bus3	Bus4	0.08400	0.33600	0.04100	
3	1	3	Bus3	Bus5	0.05300	0.21000	0.02550	
3	1	4	Bus4	Bus5	0.06300	0.25200	0.03050	

GENERATOR DATA		
FROM NODE	FROM NAME	STATUS 0/3
1	Bus1	3
3	Bus3	3

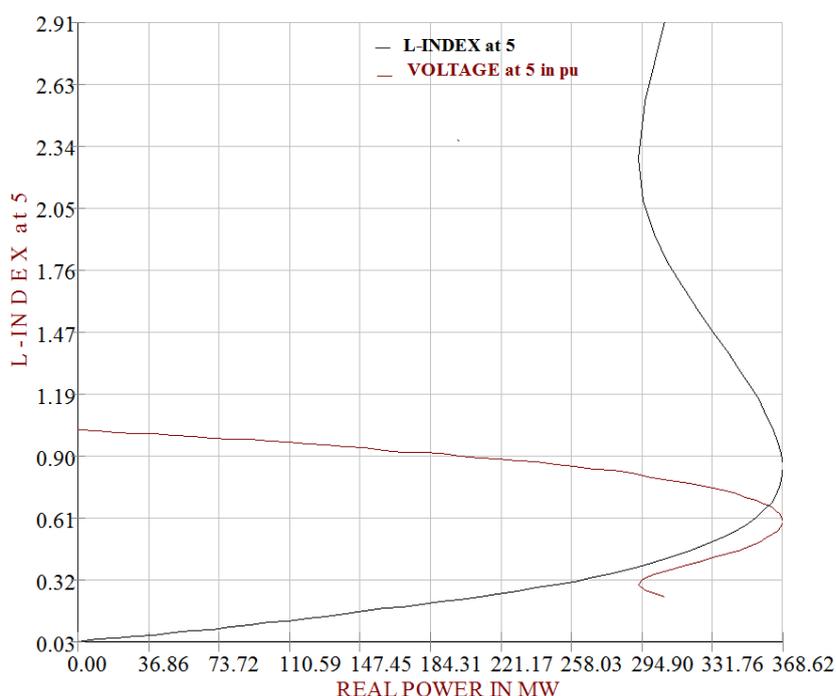
CENTROID VOLTAGE OF GENERATOR BUS VOLTAGES : (1.028929) + (j -0.033030)

L INDEX VALUE AND VCPI(Centroid) FOR THE SYSTEM AT GIVEN OPERATING CONDITION

SLNO	BUSNO	NAME	VOLT-MAG	L-INDEX	VCPI-Centroid
1	2	Bus2	0.961413	0.104364	0.107531
2	5	Bus5	0.968310	0.107694	0.100186
3	4	Bus4	0.920314	0.200256	0.204699

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RESULTS OF VOLTAGE INSTABILITY ANALYSIS



VIII. CONCLUSION

Power flow or load flow studies exhibit significant importance for power system planning and operation. This paper represents the load flow and Voltage instability analysis of 5 bus system using Fast decoupled method by MiPower software. This software helps to solve the load flow technique in an efficient manner and leads the system to effective utilization of power and voltage. The principal information obtained from the power flow study is the magnitude and phase angle of the voltage at each bus, and the real and reactive power flowing in each line. L(line) index is proposed as a good voltage stability indicator with its value change between zero (no load) and one (voltage collapse) In voltage instability analysis we get L Index value at Bus number 2,4 and 5 which is shown in voltage instability result report. Graphical analysis between real power and L Index with voltage at bus number 5 has also been depicted.

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